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*wish to have a volume flow rate of 10 million gallons ( $3.79 \times 10^4 \text{m}^3$ ) per day, and the m...*

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*21/1/2016 · 4. The difference of vectors  $A$  and  $B$ , represented by  $A - B$ , is that vector  $C$  which added to  $B$  yields vector  $A$ . Equivalently,  $A - B$  can be defined as the sum  $A + (-B)$ . If  $A = B$ , then  $A - B$  is defined as the null or zero vector and is represented by the symbol  $0$  or simply  $0$ . ...*

**Rotation matrix for rotations  
around y-axis - MATLAB roty**

*R = roty(ang) creates a 3-by-3 matrix used to rotate a 3-by-1 vector or 3-by-N matrix of vectors around the y-axis by ang degrees. When acting on a matrix, each column of the matrix represents a different vector. For the rotation matrix R and vector v, the rotated vector is given by  $R*v$ .*

**Rotation matrix for rotations  
around z-axis - MATLAB rotz**

*R = rotz(ang) creates a 3-by-3 matrix used to rotate a 3-by-1 vector or 3-by-N matrix of vectors around*

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*the z-axis by  $\alpha$  degrees. When acting on a matrix, each column of the matrix represents a different vector. For the rotation matrix  $R$  and vector  $v$ , the rotated vector is given by  $R*v$ .*

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